

# A new studded precast concrete sandwich wall with embedded glass-fiber-reinforced polymer channel sections: Part 2, finite element analysis and parametric studies

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- This paper presents the finite element analysis (FEA) modeling of precast concrete sandwich panels with glass-fiber-reinforced polymer channel sections used as shear connectors.
- The validity of the FEA models was confirmed with the results from the experimental testing performed in a previous related study.
- The effect of channel connector geometry, concrete compressive strength, and concrete wythe reinforcement ratio on the precast concrete sandwich panel stiffness, strength, and degree of composite action was investigated.
- The results indicate that adjustments can be made to the panel design that improve the thermal efficiency of the panel without compromising the structural performance.

Concrete sandwich panels have been used in the construction industry for more than 50 years, typically for building envelopes.<sup>1</sup> They are commonly composed of outer and inner wythes made of reinforced or prestressed concrete with rigid insulation sandwiched between the wythes to provide maximum thermal insulation. Concrete sandwich panels can be structurally classified as either fully composite, partially composite, or noncomposite.<sup>1-3</sup> The distinction among these three types of panels is based on the amount of horizontal shear transferred from one concrete wythe to the other through shear connectors in the form of solid concrete regions, discrete ties, trusses, and mesh grids.<sup>1,4-6</sup> In noncomposite panels, the concrete wythes act independently because the connectors linking them have negligible shear resistance.<sup>7</sup> The wythes can both be structural, but commonly one of them resists the loads while the other functions as a protective layer for the insulation foam core and as an architectural facade. In the case of fully composite panels, the two wythes act as a single unit through properly designed shear connectors, which are able to resist all of the horizontal shear.<sup>7</sup>

Partially composite panels are the general case, in which the connectors do not transfer the full shear.<sup>8</sup> Although the design and analysis of fully composite and noncomposite panels are simple and straightforward using the principles of force equilibrium and strain compatibility, partially composite panels pose a challenge because of the complexity of behavior and uncertainty about the amount of shear transferred across the wythes. The degree of composite action

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of concrete sandwich panels is generally quantified through experimental tests combined with simplified analysis.<sup>7</sup> Experimental tests, though expensive and time consuming, are still needed to confirm the effectiveness of new panel designs and validate the results of numerical methods.<sup>2,5-10</sup>

A number of analytical models have been developed to study the performance of partially composite concrete sandwich panels. Hamed<sup>11</sup> presented a theoretical model for concrete sandwich panels with a steel truss connector. The model uses the principles of equilibrium and constitutive material models and accounts for axial and bending rigidities, cracking of concrete wythes, shear and normal rigidities of insulation foam, and elastic flexibility of the connector. A parametric study was also presented on the effects of the diameter and inclination angle of the truss connector and the thickness of concrete wythes and insulation layer. In a later study, Hamed<sup>12</sup> used the previously mentioned analytical model to investigate concrete sandwich panels with a diagonal shear connector made of fiber-reinforced polymer (FRP) bars. The model presented in the later study incorporated several revisions since the earlier study, including tension stiffening of concrete and a nonlinear stress-strain relationship for concrete in compression, yielding of steel wythe reinforcement, and expected failure modes. Tomlinson and Fam<sup>3,4</sup> also developed theoretical models to predict the behavior of concrete sandwich panels connected by angled basalt-FRP bars under flexural loads<sup>3</sup> and axial loads.<sup>4</sup>

Finite element analysis (FEA) has become widely popular in the past few decades. If properly calibrated with test data, FEA can significantly reduce the time and cost of research projects compared with additional experimental testing. One of the early FEA studies on concrete sandwich panels is by Bush and Wu,<sup>13</sup> who used solid elements for concrete and insulation and truss elements for the connectors with a linear solution. The model resulted in a conservative prediction of the panels' strength and stiffness. Lee and Pessiki<sup>14</sup> developed an FEA element model for two- and three-wythe panels and incorporated prestressing effects. Hopkins<sup>15</sup> used the FEA software Abaqus to develop a nonlinear model for concrete sandwich panels connected by segmental FRP plates under blast loads. A concrete damage plasticity model was implemented to simulate the behavior of concrete in tension and compression. The FEA model by Henin et al.<sup>16</sup> used shell elements to model the concrete and insulation and bar elements for the connectors, but the models were only applicable to service load levels.

In this study, comprehensive nonlinear FEA models were developed for the new concrete sandwich panel design presented in the companion paper.<sup>17</sup> The models incorporated various material and geometric features, including concrete nonlinearity and crushing in compression, concrete cracking and stiffening in tension, interfacial laws for parts in contact (for example, concrete to glass-fiber-reinforced polymer [GFRP] channel, concrete to insulation, and insulation to GFRP channel interfaces), steel plasticity, failure of GFRP channel using

the Hashin model,<sup>18</sup> and geometric nonlinearity and buckling failure. The models were verified against the experimental results in the companion paper and used in a parametric study to examine the effects of steel reinforcement ratio, the ratio between the unsupported depth of the channel (which is equal to the insulation thickness) and the channel web thickness  $d_w/t_w$ , the channel flange thickness  $t_f$ , and concrete compressive strength. The effects of introducing openings in the GFRP channel web to reduce thermal bridging were studied in terms of shape and size of the opening (for example, diameter  $D$  and clear spacing  $S$  of circular openings).

## FEA model development

The FEA models were developed in Ansys APDL commercial software. The three-dimensional panel model consisted of the two reinforced concrete wythes, insulation layer, GFRP channel connector, and steel plates at the loading and support locations. Symmetry conditions were applicable in the longitudinal direction but not in the transverse direction due to the unsymmetrical shape of the GFRP connector. Hence, the model was generated for half of the panel length and the entire width (Fig. 1).

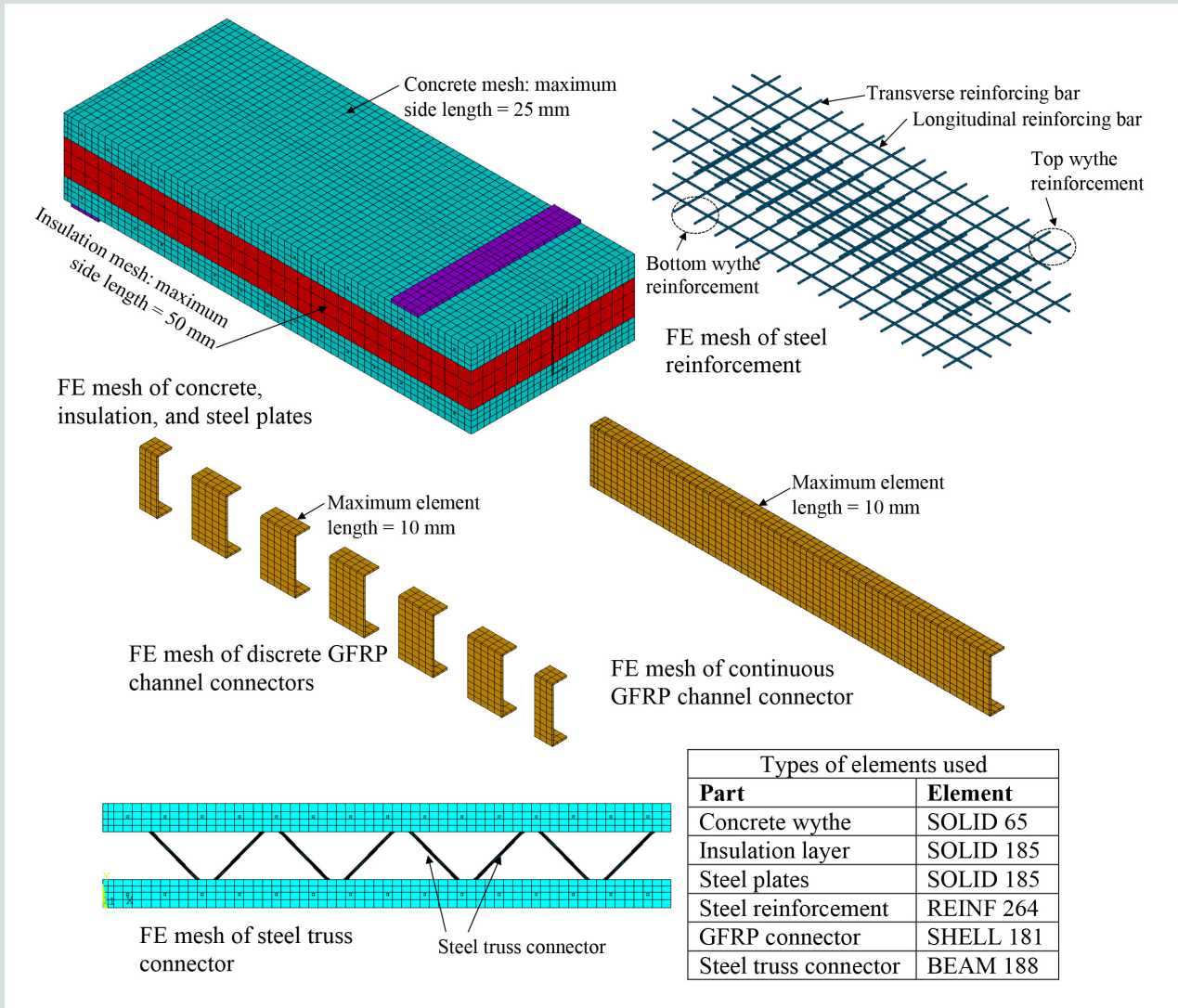
## FEA mesh and boundary conditions

The concrete wythes were modeled using cubic elements with a maximum side length of 25 mm (1 in.) (Fig. 1). The maximum element length of the cubes was increased to 50 mm (2 in.) for the insulation layer because of its negligible structural stiffness and strength (Fig. 1). The GFRP channel was meshed with one shell element through the thickness and multiple elements in the other two directions, with a maximum element length of 10 mm (0.4 in.) (Fig. 1). The boundary conditions consisted of a roller restraint ( $U_y = 0$ ) at the support and symmetry conditions at midspan for the half-length model. All nodes were restrained at the midspan section in the  $x$  direction ( $U_x = 0$ ) (Fig. 1). Additional rotational restraints ( $\theta_y = \theta_z = 0$ ) were applied to the channel section nodes at midspan because the channel was modeled with shell elements that had translational and rotational degrees of freedom (DOFs). The applied load was modeled as nonzero vertical displacements (Fig. 1) to accurately capture the load history, including the decrease in load after local damage (for example, concrete crushing, FRP rupture, and debonding) and the postfailure response.

## Element types

Multiple types of elements were used to model the different parts of the concrete sandwich panel (Fig. 1). These elements are summarized in this section.

**SOLID65** The concrete wythes were modeled with the eight-node SOLID65 element available in the Ansys library. This element, whose nodes have three translational DOFs, has special features for modeling brittle materials such as concrete and soil. The element is capable of modeling concrete's



**Figure 1.** Finite element model. Note: FE = finite element; GFRP = glass-fiber-reinforced polymer. 1 mm = 0.0394 in.

nonlinear stress-strain response in compression, crushing, and cracking in three orthogonal directions and tension stiffening after cracking.

**SOLID185** The insulation layer and steel plates at the support and loading locations were modeled with the eight-node SOLID185 element. Similar to the concrete element, SOLID185 nodes also have three translational DOFs in the x, y, and z axes. The element is capable of modeling nonlinear material stress-strain responses, plasticity, stress stiffening, and large deformations.

**REINF264** The steel wire mesh used as longitudinal and transverse reinforcement for the concrete wythes was modeled with the REINF264 element. The element has two nodes, each with three translational DOFs, and is capable of modeling axial (tension, compression, or both) behavior only. Assigned to a base solid element, SOLID65 in this

case, the nodes of REINF264 are coupled with the base element nodes, thus assuming that the slip between steel mesh and concrete is negligible.

**SHELL181** The GFRP channel connector was modeled using a four-node shell element (SHELL181). The element has six DOFs, three translational and three rotational, and is suited for analyzing thin to moderately thick shell structures with large strain, rotation, deformation, and nonlinear material responses. In this study, a reduced integration option with hourglass control was activated to prevent inaccurate results associated with shell distortion.

**BEAM188** For the reference panel with steel truss connector (specimen TR in the companion paper<sup>17</sup>), the truss was modeled using beam element BEAM188. The beam element is defined by two nodes, each having six DOFs, three translational and three rotational. The beam element was selected because

it includes bending and shear deformation effects, necessary for simulating the rigid truss connector and its dowel action of transferring horizontal shear. In addition, connector buckling and stability failures can be captured by activating the geometric nonlinearity algorithm.

**CONTA173** For any surfaces in contact (for example, the GFRP channel with concrete), a surface-to-surface contact-target pair of elements was inserted to simulate the interfacial contact and sliding behavior. The contact element CONTA173 has four nodes and was placed on the surface containing softer material or finer FEA mesh, as recommended by Ansys. On the other surface, a companion target element, TARGE170, was placed. In addition to the contact-target pair, a bond-slip relation or cohesive zone model is needed to define the interface behavior in the normal and tangential directions. This is discussed in the following section.

## Interfacial models

An interfacial relation, such as a bond-slip model or frictional law, is needed to model the contact-target elements. In the case of the concrete sandwich panels investigated here, three surfaces were found to be in contact:

- concrete and GFRP channel connector at the embedded part of the channel (interface 1)
- GFRP channel and insulation at the unsupported section of the channel web (interface 2)
- concrete and insulation (interface 3)

**Interface 1** For the concrete-channel interface, a frictional contact model was used in the tangential direction. This model better relates to the interface, given its low bond strength of 0.28 MPa (0.04 ksi) and the large amount of slip recorded at the wythe ends, as determined experimentally in the companion paper.<sup>17</sup> The Mohr-Coulomb friction model available in Ansys was used for this interface and is defined as follows:

$$\tau = COHE + \mu \times N \quad (1)$$

where

$\tau$  = interface shear stress

$COHE$  = interface cohesion when stress  $\sigma = 0$ , which is the 0.28 MPa (0.04 ksi) bond strength measured from the push-off specimens

$\mu$  = coefficient of friction

$N$  = normal contact pressure

A value of 0.2 was used for the friction coefficient  $\mu$  of the GFRP section.<sup>19</sup> Sliding (tangential slip) between the

two surfaces occurs when the shear stresses acting on the interface exceed  $\tau$  in Eq. (1). In the direction normal to the concrete-channel interface, a full contact behavior (realized in Ansys by the no-separation option) was assumed because the channel was embedded in concrete, restraining the normal movement between the two parts.

**Interface 2** The unsupported web of the channel could initially be in contact with the insulation, or the contact might develop after bending. Although the behavior of this interface was not expected to affect the behavior of the panel, the interface contact was also modeled. A frictionless contact was assumed, which allows the contacting surfaces to freely slide relative to each other but not interpenetrate normally. The  $COHE$  and  $\mu$  parameters were set to zero.

**Interface 3** The interface between concrete and insulation was not expected to develop any shear stresses because the insulation layer was wrapped with a bond-breaking sheet to prevent insulation adhesion and friction bond. Therefore, a frictionless contact, similar to the one used at interface 2, was also used for the concrete-insulation interface.

## Material properties

**Concrete wythes** A nonlinear uniaxial stress-strain model proposed by Kent and Park<sup>20</sup> was used to represent the concrete compressive behavior (**Fig. 2**). The following mathematical expressions define the concrete model:

$$f_c = f'_c \left[ 2 \left( \frac{\epsilon}{\epsilon_0} \right) - \left( \frac{\epsilon}{\epsilon_0} \right)^2 \right] \quad \text{for } 0 \leq \epsilon \leq \epsilon_0$$

$$f_c = f'_c \left[ 1 - Z(\epsilon - \epsilon_0) \right] \quad \text{for } \epsilon > \epsilon_0$$

where

$f_c$  = compressive stress at any strain  $\epsilon$

$f'_c$  = concrete compressive strength

$\epsilon$  = stress

$\epsilon_0$  = strain at  $f'_c$ , which can be expressed as  $\epsilon_0 = \frac{2f'_c}{E_c}$

$Z$  = the slope of the linear descending portion of the stress-strain curve for concrete in compression

$\epsilon_c$  = concrete strain

$E_c$  = concrete elastic modulus, calculated as

$E_c = 4700 \sqrt{f'_c}$  following the American Concrete Institute's *Building Code Requirements for Structural Concrete (ACI 318-14) and Commentary (ACI 318R-14)*.<sup>21</sup>

The slope  $Z$  of the linear descending portion in the graph labeled “Concrete in Compression” in Fig. 2 is determined as follows for unconfined concrete:

$$Z = \frac{0.5}{\epsilon_{50u} - \epsilon_0}$$

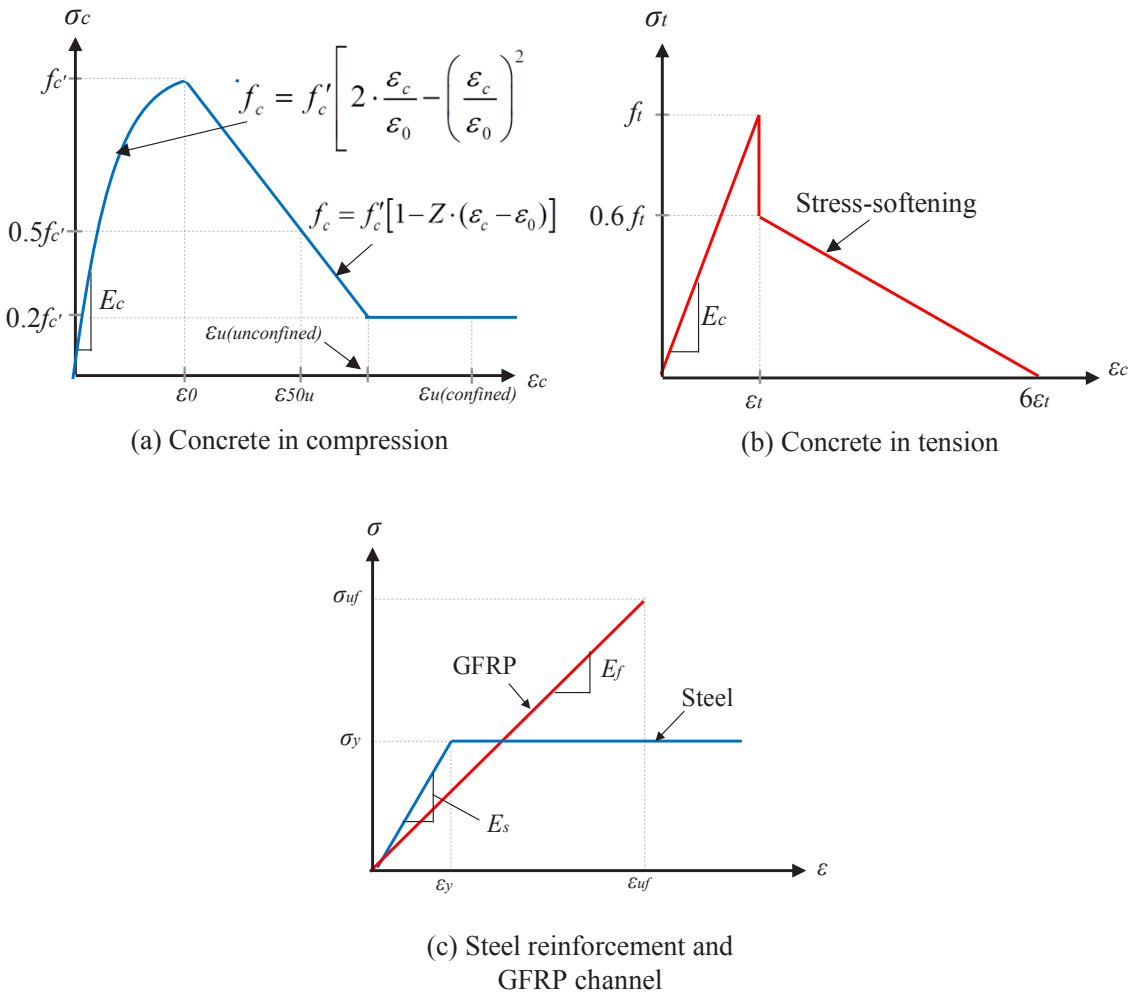
where

$\epsilon_{50u}$  = strain at  $f_c = 0.5f'_c$ , which can be expressed as

$$\epsilon_{50u} = \frac{30 + 0.002f'_c}{f'_c - 1000}$$

The concrete tensile stress-strain response was modeled as linear elastic before cracking at a maximum tensile stress  $f_t$  of  $0.56\sqrt{f'_c}$  as defined by ACI 318.<sup>21</sup> Tension-stiffening effects were modeled with a linear descending curve ending at a strain of  $6\epsilon_t$ , where  $\epsilon_t$  is the strain at  $f_t$  (Fig. 2). A value of 0.2 was used for the open and closed shear transfer coefficients.<sup>22,23</sup> The Poisson’s ratio of concrete was assumed to be 0.2.<sup>22,23</sup>

**Steel** For the steel wire mesh, which was used as flexural reinforcement for the concrete wythes and the steel truss connector in the reference panel (specimen TR in the com-



**Figure 2.** Stress-strain models used in finite element analysis simulation. Note:  $E_c$  = concrete elastic modulus;  $E_f$  = elastic modulus of GFRP channel;  $E_s$  = elastic modulus of steel;  $f'_c$  = concrete compressive stress at any strain;  $f'_c$  = concrete compressive strength;  $f_t$  = maximum concrete tensile stress; GFRP = glass-fiber-reinforced polymer;  $Z$  = slope of the linear descending portion of the stress-strain curve for concrete in compression;  $\epsilon$  = strain;  $\epsilon_c$  = concrete strain;  $\epsilon_t$  = strain at the maximum concrete tensile stress;  $\epsilon_u$  = ultimate concrete compressive strain;  $\epsilon_{uf}$  = ultimate strain in the GFRP channel;  $\epsilon_y$  = yield strain in the steel reinforcement;  $\epsilon_0$  = concrete compressive strain at  $f'_c$ ;  $\epsilon_{50u}$  = concrete compressive strain at  $f_c$  equal to  $0.5f'_c$ ;  $\sigma$  = stress;  $\sigma_c$  = concrete compressive stress;  $\sigma_t$  = concrete tensile stress;  $\sigma_{uf}$  = ultimate stress of GFRP channel;  $\sigma_y$  = yield stress of steel reinforcement;  $\sigma$  = stress;  $\sigma_c$  = concrete compressive stress;  $\sigma_t$  = concrete tensile stress;  $\sigma_{uf}$  = ultimate stress of GFRP channel;  $\sigma_y$  = yield stress of steel reinforcement.

panion paper),<sup>17</sup> an elastic–perfectly plastic model was used (Fig. 2). The yield stress  $f_y$  was measured experimentally as 485 MPa (70.3 ksi). The elastic modulus  $E_s$  and Poisson’s ratio  $\nu$  for steel were assumed to be 200 GPa (29,000 ksi) and 0.3, respectively.

**GFRP channel** A linear elastic model was assumed for the GFRP channel (Fig. 2), whose properties in the direction parallel to fibers are different from the properties in other directions, also known as a specially orthotropic and transversely isotropic material.<sup>24</sup> **Table 1** lists the material properties for the channel section. In the experimental testing (presented in the companion paper),<sup>17</sup> failure in the channel was the governing failure mode of the panel, at which ultimate load was reached, followed by a sharp decrease in load.

To predict the panel’s global behavior, including ultimate strength, accurate modeling of channel failure is needed. The composite damage model available in Ansys for FRP materials, known as the material property degradation method (MPDG), was used to simulate the failure mechanism of the GFRP channel. The model can predict five failure modes commonly observed in FRPs:

- fiber tension
- fiber compression
- matrix tension
- matrix compression
- interlaminar shear

Within the MPDG, a failure criterion defines the initiation of failure in any of the five failure modes when the stress or strain limit is reached. In this study, the Hashin failure criteria,<sup>18</sup> which are widely used in the literature,<sup>25,26</sup> have been adopted. **Table 2** lists the mathematical terms for defining the different FRP failure modes based on the Hashin criteria. In

**Table 1.** Mechanical properties of GFRP channel

Stiffness	Elastic modulus in fiber direction $E_1$ , MPa	23 <sup>†</sup>
	Elastic modulus in matrix direction $E_2$ , MPa	9.32 <sup>*</sup>
	Major Poisson’s ratio $\nu_{12}$	0.33 <sup>*</sup>
	Shear modulus $G_{12}$ , MPa	2.93 <sup>*</sup>
Strength	Tensile strength in fiber direction $X^T$ , MPa	367 <sup>*</sup>
	Compressive strength in fiber direction $X^C$ , MPa	-186 <sup>*</sup>
	Tensile strength in matrix direction $Y^T$ , MPa	123 <sup>*</sup>
	Compressive strength in matrix direction $Y^C$ , MPa	-103 <sup>*</sup>
	In-plane shear strength $S^L$ , MPa	39 <sup>*</sup>

Note: 1 MPa = 0.145 ksi.

\* Determined from experimental tests in the companion paper. In case two values were reported for the flange and web, the lowest value was used in modeling the entire channel section.

† Taken from the manufacturer.

**Table 2.** Fiber-reinforced polymer damage model for channel connector

FRP failure mode	Governing stress	Hashin failure criteria
Fiber tension failure	$\sigma_{11} \geq 0$	$= \left( \frac{\sigma_{11}}{X^T} \right)^2 + \left( \frac{\tau_{11}}{Z^L} \right)^2$
Fiber compression failure	$\sigma_{11} < 0$	$= -\frac{\sigma_{11}}{X^C}$
Matrix tension failure	$\sigma_{11} > 0$	$= \left( \frac{\sigma_{22}}{Y^C} \right)^2 + \left( \frac{\tau_{12}}{S^L} \right)^2$
Matrix compression failure	$\sigma_{22} < 0$	$= \left( \frac{\sigma_{22}}{Y^C} \right)^2 + \left[ \left( \frac{Y^C}{2S^L} \right)^2 - 1 \right] \frac{\sigma_{22}}{Y^C} + \left( \frac{\tau_{12}}{S^L} \right)^2$
Fiber-matrix shear failure	$\sigma_{22} + \sigma_{33} > 0$	$= \left( \frac{\sigma_{11}}{X^T} \right)^2 + \left( \frac{\tau_{12}}{S^L} \right)^2$

Note: FRP = fiber-reinforced polymer;  $S^L$  = in-plane shear strength;  $X^C$  = compressive strength in fiber direction;  $X^T$  = tensile strength in fiber direction;  $Y^C$  = compressive strength in matrix direction;  $\sigma_y$  = acting normal stress;  $\tau_y$  = acting shear stress.

In addition to the failure criteria, a damage evolution criterion defines the material degradation after reaching the stress or strain limit. An instant stiffness reduction factor of 0.99 was applied to each affected mode and was selected based on previous work.<sup>27</sup>

### Model verification

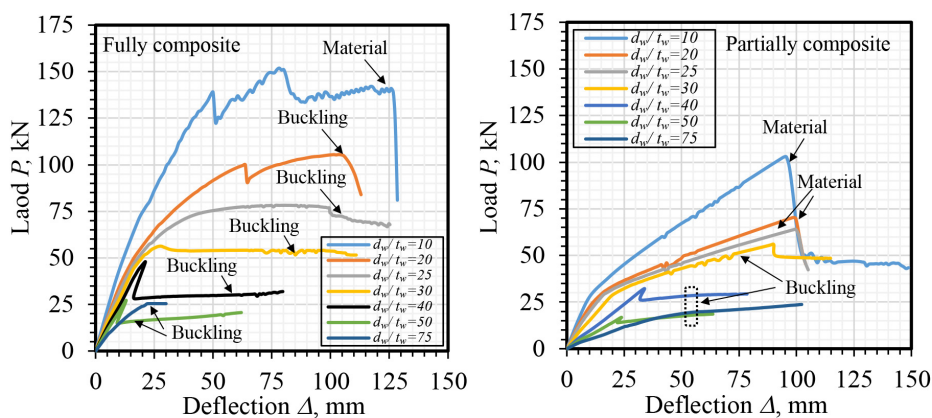
The load  $P$  compared with midspan deflection  $\Delta$  plots presented in the companion paper<sup>17</sup> compare the FEA prediction with the experimental results. In general, the FEA models showed reasonable agreement with the experimental results and were able to simulate the entire experimental panel behavior, including failure and postfailure stages. The FEA responses, however, were slightly stiffer for some of the tested panels.

The companion paper also compared the experimental and predicted maximum loads  $P_{max}$  for the five tested panels. The percentage difference between the predicted and experimental

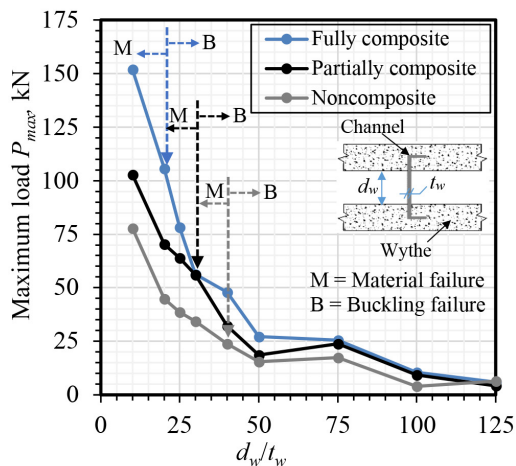
loads was 2% to 17%. The FEA simulations of the channel connector failure were an excellent match to the experimental results. By implementing the composite damage concept along with Hashin failure criteria, the models were able to accurately capture various channel failures, such as compression in top flange, shear in the web, and tension in the web and bottom flange. Furthermore, the models were also capable of simulating the slipping behavior at the three contact interfaces: concrete–channel, concrete–insulation, and insulation–channel.

### Parametric study

The validated FEA model was used in a comprehensive parametric study using 70 individual model runs to examine the effects of several key parameters expected to affect the behavior of the concrete sandwich panel with a GFRP channel connector. The parameters studied were channel unsupported depth (insulation thickness)–to–web thickness ratio, channel flange thickness, concrete compressive strength, and



Load  $P$  compared with deflection  $\Delta$  for fully and partially composite panels



**Figure 3.** Effects of unsupported channel depth–to–web thickness ratio. Note:  $d_w$  = unsupported channel depth;  $t_w$  = channel web thickness. 1 mm = 0.0394 in.; 1 kN = 0.225 kip.

steel reinforcement ratio in the concrete wythes. The effect of introducing web openings in the GFRP web to minimize thermal bridging was also explored numerically, including variations of the shape of the opening and the diameter and spacing for circular openings. For some of these parameters, the analysis was performed for the two extreme conditions of fully composite and noncomposite panels, in addition to the actual case of partially composite panels.

Fully composite panels were idealized numerically by having the channel perfectly bonded to the concrete wythe (bonded contact), while still considering frictionless (unbonded) contact at the concrete–insulation and insulation–channel interfaces. On the other hand, the noncomposite panels were created by assuming that the concrete–channel interface was frictionless, similar to the other two interfaces.

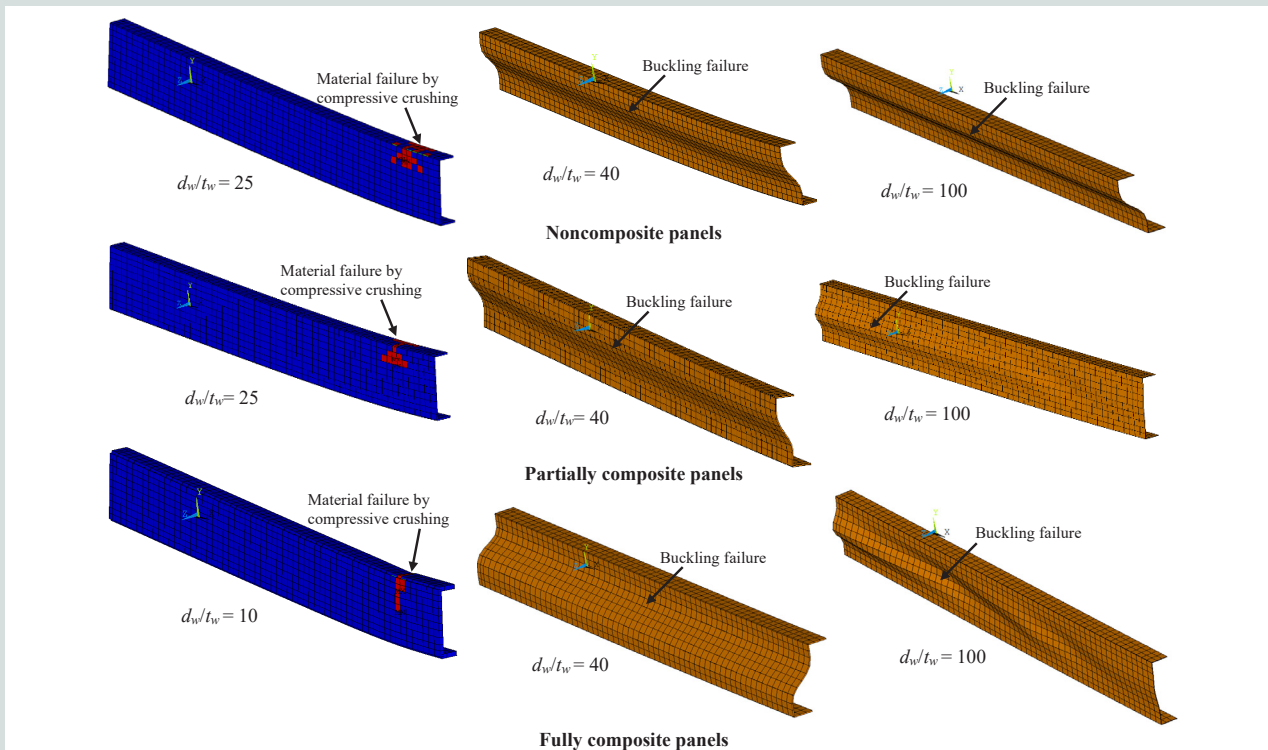
### Unsupported channel depth-to-thickness ratio $d_w/t_w$

The effects of the ratio of unsupported channel depth  $d_w$  to web thickness  $t_w$  on the panel behavior were studied by varying  $t_w$  from 1 to 13 mm (0.04 to 0.5 in.) such that  $d_w/t_w$  varied from 10 to 125. It is expected that increasing  $d_w/t_w$  will change the failure mode from material rupture to web buckling (stability failure). Local buckling is a commonly observed failure mode in thin-walled pultruded FRP sections with low modulus, such as GFRP.<sup>28,29</sup> To capture the stability failure

in the FEA, a geometric nonlinearity algorithm was activated, which resulted in longer run times but more accurate results.

**Figure 3** shows the load  $P$  compared with deflection  $\Delta$  for the fully and partially composite panels with different  $d_w/t_w$ . **Figure 4** also plots the maximum load  $P_{max}$  against  $d_w/t_w$  for the noncomposite, partially composite, and fully composite panels. Two failure modes were observed: material failure by compressive crushing in the channel flange and web and stability failure by channel web buckling. The transition from material to stability failure occurred at  $d_w/t_w$  equal to 20, 30, and 40 for the fully composite, partially composite, and noncomposite panels, respectively. As  $d_w/t_w$  increased, the strength and stiffness of the panel decreased (**Fig. 3**). Compared with material failure, the specimens with buckling failure (lower  $d_w/t_w$ ) showed a more ductile behavior after reaching the peak load (**Fig. 3**). **Figure 3** shows that for all three cases,  $P_{max}$  decreased sharply, by 82% on average, when  $d_w/t_w$  increased from 10 to 50. Beyond  $d_w/t_w$  equal to 50,  $P_{max}$  decreased at a much lower rate.

**Figure 4** shows the material and stability failures in channel connectors with various  $d_w/t_w$  and degrees of composite action. In general, the material failure of compression crushing in the channel flange and web near midspan was identical for all observed cases and is shown by the red elements in **Fig. 4** with a Hashin damage parameter of 1.0. However, the stability failure was variable, depending on  $d_w/t_w$  and degree of composite action. In some specimens, stability failure



**Figure 4.** Channel material and stability failures for fully composite, partially composite, and noncomposite panels and different values of  $d_w/t_w$ . Note:  $d_w$  = unsupported channel depth;  $t_w$  = channel web thickness.

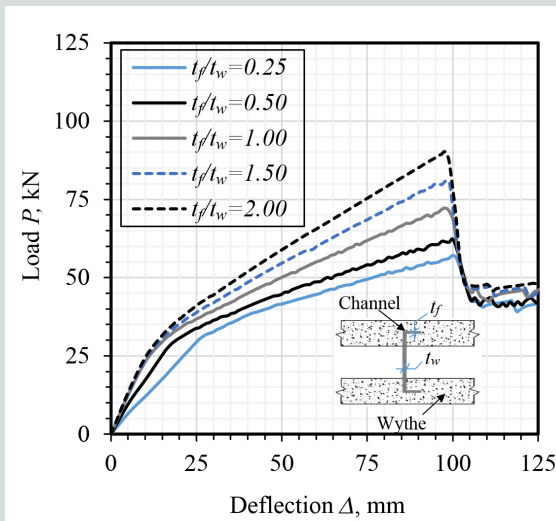


occurred throughout the entire channel length as a uniform second-order mode, as seen in Fig. 4 with  $d_w/t_w$  equal to 40, whereas in other specimens, buckling appeared randomly at parts of the channel, as seen in the second and third rows of Fig. 4 with  $d_w/t_w$  equal to 100. In those specimens, buckling occurred first near the supports, but as the load increased buckling approached the midspan region.

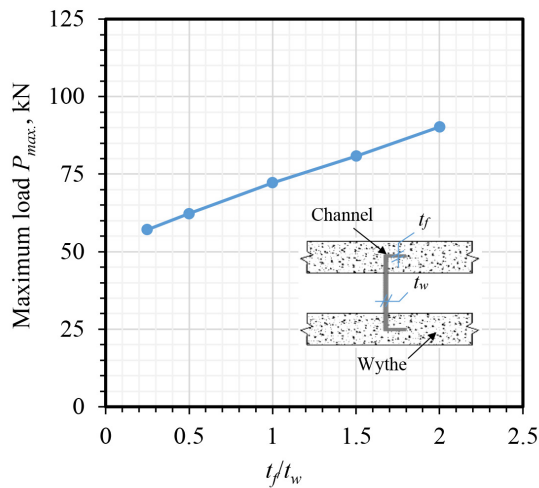
### GFRP flange thickness $t_f$

Similar to the channel web thickness  $t_w$  investigated in the previous section, the effects of channel flange thickness  $t_f$  are explored in this section by varying the ratio of GFRP channel

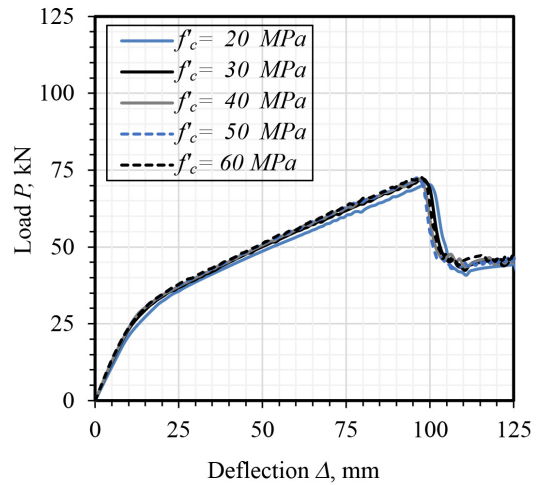
flange thickness-to-web thickness  $t_f/t_w$  from 0.25 to 2 for the partially composite panels. **Figure 5** displays the load-deflection responses for panels with different  $t_f/t_w$  and the relation between  $P_{max}$  and  $t_f/t_w$ . Increasing  $t_f/t_w$  resulted in an increase in the stiffness and ultimate load. However, the deflection at ultimate load remained constant at around 100 mm (4 in.), indicating that  $t_f$  has negligible effects on deformability. The panel failure was governed by the channel compressive crushing that occurred simultaneously in the top flange and web. A linear increase in  $P_{max}$  in relation to  $t_f/t_w$  is shown in Fig. 5, with  $P_{max}$  increasing by 25% when  $t_f$  was doubled from  $1.0t_w$ , which was used in the experimental testing described in the companion paper,<sup>17</sup> to  $2.0t_w$ .



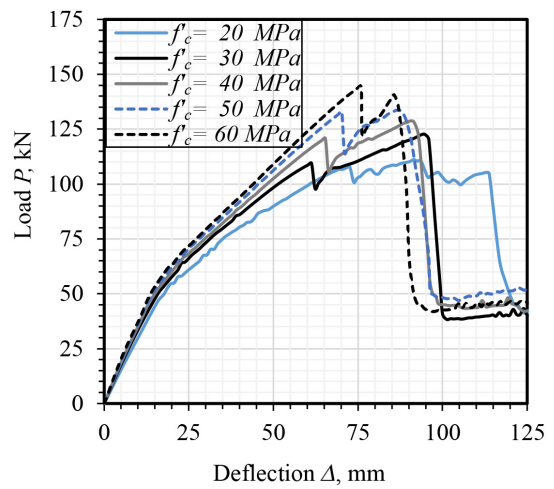
Load  $P$  compared with deflection  $\Delta$  curves



Maximum load  $P_{max}$  compared with  $t_f/t_w$



Partially composite panels



Fully composite panels

**Figure 5.** Channel material and stability failures for fully composite, partially composite, and noncomposite panels and different values of  $d_w/t_w$ . Note:  $d_w$  = unsupported channel depth;  $t_w$  = channel web thickness.

**Figure 6.** Load compared with deflection plots, with different concrete compressive strengths. Note:  $f'_c$  = concrete compressive strength. 1 mm = 0.0394 in.; 1 kN = 0.225 kip; 1 MPa = 0.145 ksi.

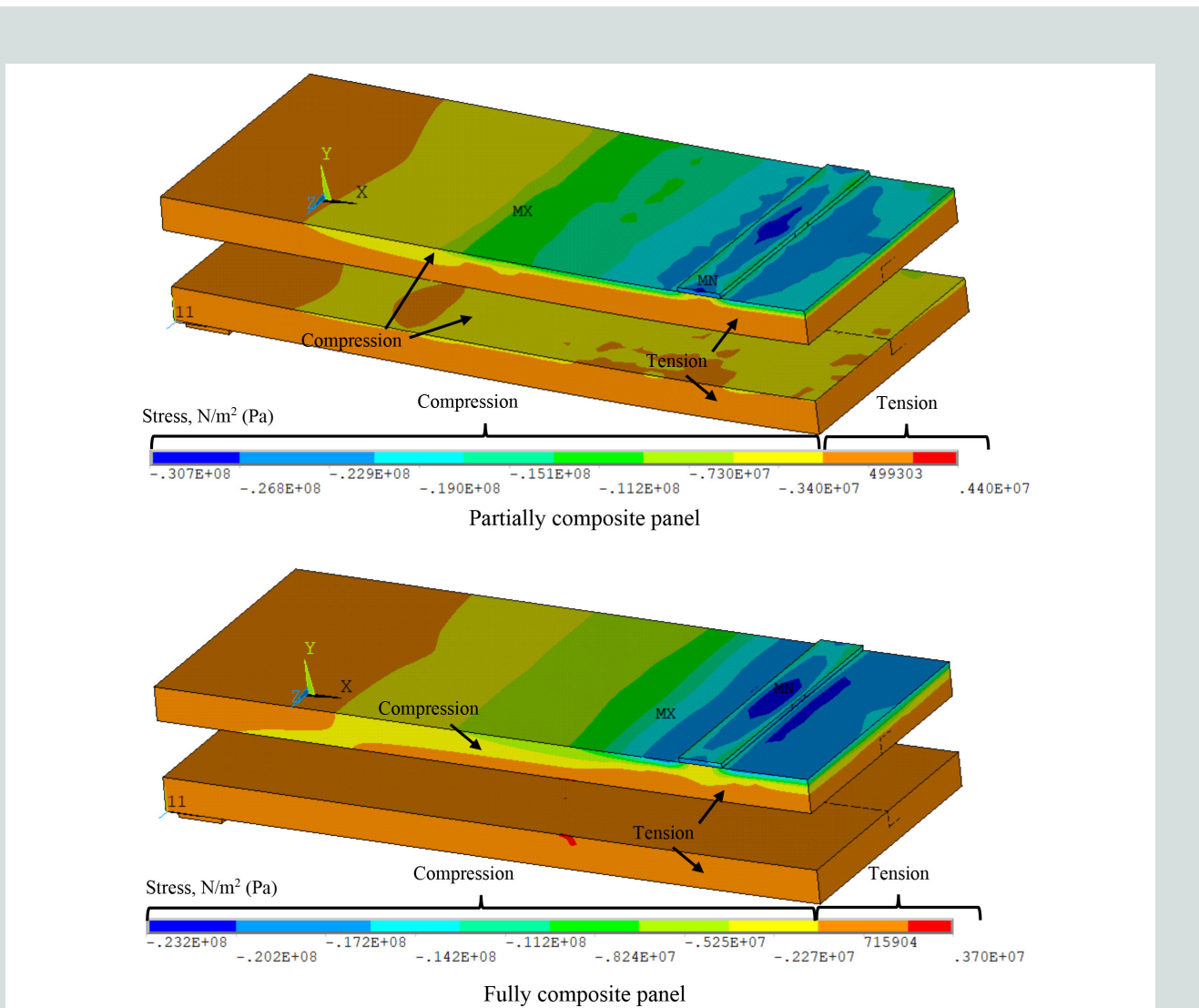
## Concrete compressive strength $f'_c$

The concrete compressive strength  $f'_c$  varied from 20 to 60 MPa (2.9 to 8.7 ksi) for the partially and fully composite panels. For each  $f'_c$ , new tensile and compressive stress-strain models were generated, according to the constitutive modeling presented earlier. **Figure 6** shows the load-deflection responses for the partially and fully composite panels. The top graph in Fig. 6 shows that the structural behavior of the partially composite panels was not largely affected by  $f'_c$ . On the other hand, for the fully composite panels, increasing  $f'_c$  led to an increase in the postyielding stiffness and maximum load  $P_{max}$ , which increased by 30% when  $f'_c$  increased from 20 to 60 MPa. To understand the difference in results between partially and fully composite cases, concrete flexural stresses at an arbitrary load  $P$  equal to 50 kN (11 kip), are plotted in Fig. 7. In the partially composite panel, tensile and compressive stresses occur in each wythe (the top graph in **Fig. 7**),

indicating the presence of two neutral axes, one in each wythe. Both neutral axes are located very close to the wythe top edge, with a very small area in compression, and as such could not benefit from the increase in  $f'_c$ . For the fully composite panel, the wythes behave as a single unit, with only one neutral axis located close to the midheight of the top wythe (the bottom graph in Fig. 7). As such, the fully composite panel can gain some advantage from an increase in concrete compressive strength.

## Steel reinforcement ratio $\rho_s$

The effects of steel reinforcement ratio  $\rho_s$ , which is the area of the steel reinforcement as a percentage of the wythe cross-sectional area, are investigated in this section by varying  $\rho_s$  from 0.1% to 2.5% for the partially composite panels. For precast concrete sandwich panels, design specifications<sup>1,21</sup> provide the minimum limit of  $\rho_s$  as equal to 0.1%, with no indications of



**Figure 7.** Concrete flexural stresses at  $P = 50$  kN for wythes with  $f'_c = 60$  MPa. Note:  $f'_c$  = concrete compressive strength; MN = minimum stress in contour; MX = maximum stress in contour;  $P$  = load. 1 kN = 0.225 kip; 1 N/m<sup>2</sup> = 1 Pa = 0.000145 psi; 1 MPa = 0.145 ksi.

a maximum value. In this parametric analysis, the reinforcement ratio was controlled by changing the diameter of the reinforcing bars while keeping the number of bars constant and equal to those in specimen TR in the experimental testing described in the companion paper.<sup>17</sup> **Figure 8** shows the load-deflection relationship for different  $\rho_s$  and the variation of  $P_{max}$  with  $\rho_s$ . Increasing  $\rho_s$  resulted in a tangible increase of stiffness and ultimate load of the panel.  $P_{max}$  increased linearly and increased by 13% when  $\rho_s$  was doubled from 1% to 2%.

### Introducing web openings in the GRFP channel: Diameter of circular web openings

One of the desirable characteristics of concrete sandwich panels is their excellent thermal efficiency, which is achieved by using an insulation layer positioned between the outer and inner concrete layers to reduce thermal flow and minimize the cost of cooling and heating in buildings.<sup>1-4,7-9</sup> Shear connectors, though essential for the structural integrity of the panel, can reduce their thermal efficiency by creating thermal bridges.<sup>2</sup> The thermal resistance of concrete sandwich panels depends mainly on the connector material, size, and number.<sup>30</sup> GFRP has an inherently low thermal conductivity, averaging  $\frac{1}{60}$  to  $\frac{1}{13}$  that of steel.<sup>30</sup> However, increasing the cross-sectional area of the GFRP connector reduces thermal efficiency.<sup>31,32</sup>

This study explores the idea of introducing circular perforations in the web of the GFRP connector to minimize thermal bridging without sacrificing structural effectiveness. New FEA models were developed to examine the effect of varying the diameter of the circular opening  $D$  as a percentage of the unsupported channel depth  $d_w$ , with  $D/d_w$  ranging from 0 to 1.5 at an interval of 0.2. In all cases, the clear spacing between the openings  $S$  was kept constant at  $d_w$  and reduced to  $0.5d_w$  between the last opening and channel edge.

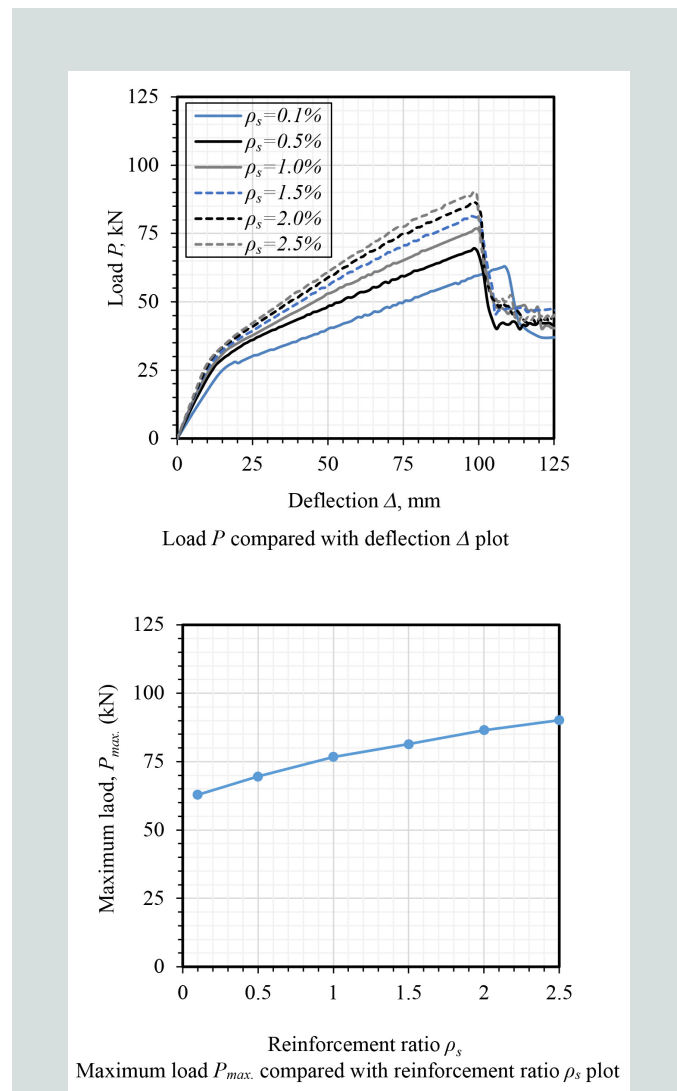
The first three graphs in **Fig. 9** show the load-deflection relationships for panels with various  $D/d_w$ , including the noncomposite, partially composite, and fully composite cases. For partially composite and noncomposite panels, the effect of circular openings on the panel stiffness is generally very small for all values of  $D/d_w$ . On the other hand, increasing the hole diameter for the fully composite panel led to a decrease in stiffness (the graph labeled “Load compared with deflection for fully composite panel” in Fig. 9). The graph labeled “Maximum load compared with  $D/d_w$ ” in Fig. 9 shows the relationship between  $P_{max}$  and  $D/d_w$ . The maximum load  $P_{max}$  remained unchanged from  $D/d_w$  equals 0 until 0.6 and 0.8 for the partially composite and noncomposite cases, respectively. Beyond these ratios,  $P_{max}$  decreased gradually. For the fully composite panel,  $P_{max}$  decreased by 16% initially when  $D/d_w$  increased from 0 to 0.4, then plateaued for  $D/d_w = 0.4$  to 0.6 and decreased again by 19% for  $D/d_w = 0.6$  to 1.0.

The material failure, indicated by the red elements, of the channel with various values of  $D/d_w$  is shown in **Fig. 10** for

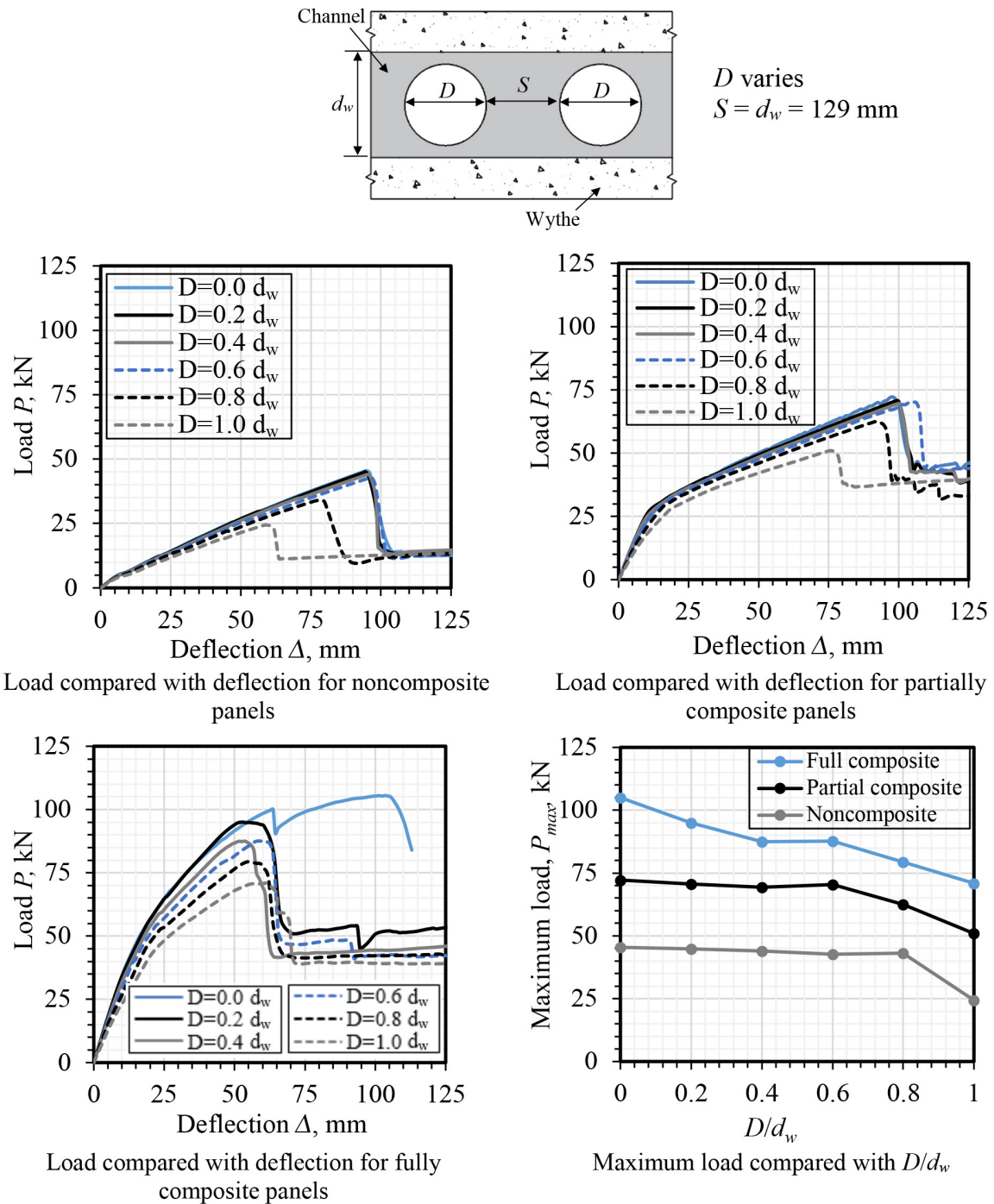
the three cases of composite action. Failure of the partially composite and noncomposite panels was by compressive crushing of channel flange and web, while for the fully composite case, the channel failed mainly by tensile rupture. As a design recommendation for the most realistic case of a partially composite panel, it is suggested that circular openings with a diameter not exceeding  $0.6d_w$  (60% of unsupported channel depth) be provided at a clear spacing of  $d_w$ , which will enhance thermal efficiency while not causing significant degradation in structural performance.

### Introducing web openings in the GFRP channel: Spacing of circular web openings

In addition to the web opening diameter  $D$ , the effects of clear spacing  $S$  between circular openings were examined for the optimal diameter  $D$  of  $0.6d_w$  established in the previous section.  $S$  was varied as a ratio of the web opening



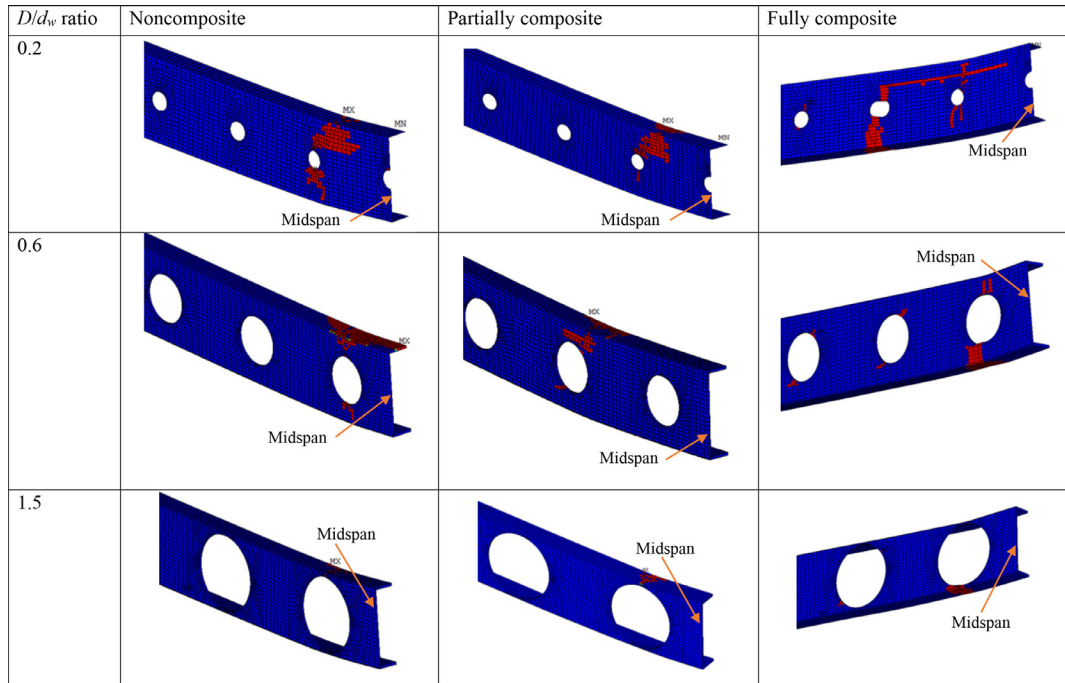
**Figure 8.** Effects of flexural reinforcement ratio  $\rho_s$ . Note: 1 mm = 0.0394 in.; 1 kN = 0.225 kip.



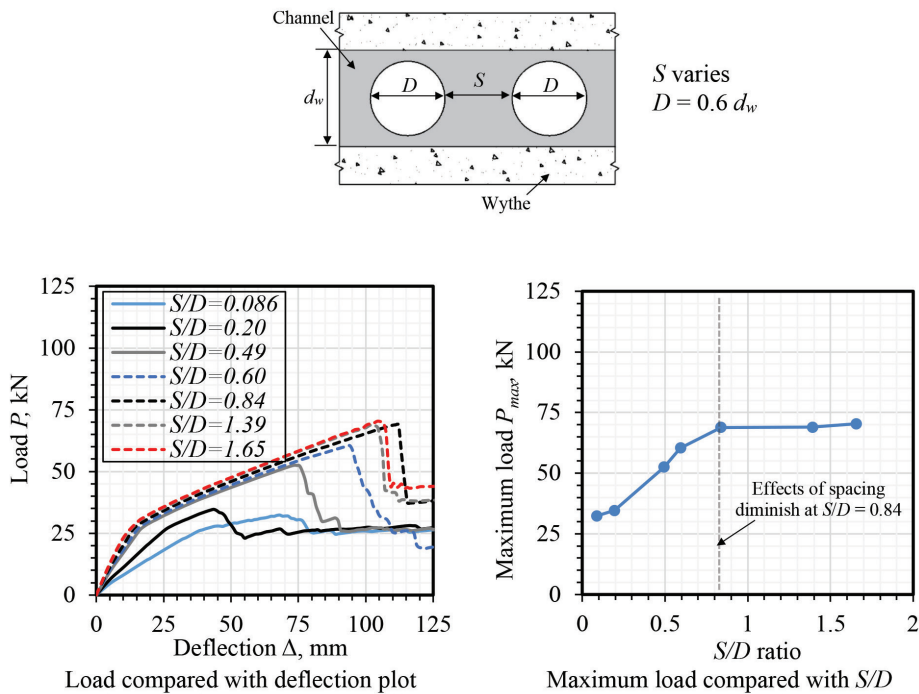
**Figure 9.** Effect of the diameter  $D$  of circular web opening in channel. Note:  $d_w$  = unsupported channel depth;  $S$  = clear spacing between circular web openings. 1 mm = 0.0394 in.; 1 kN = 0.225 kip.

diameter, with  $S/D$  ranging from 0.08 to 1.65 for the partially composite panels. **Figure 11** presents the load-deflection response and  $P_{max}$  compared with  $S/D$ . The figure shows that the global behavior was not affected when  $S/D$  was 0.84 or larger. At  $S/D$  less than 0.84, the maximum load decreased linearly and the stiffness also decreased due to the signif-

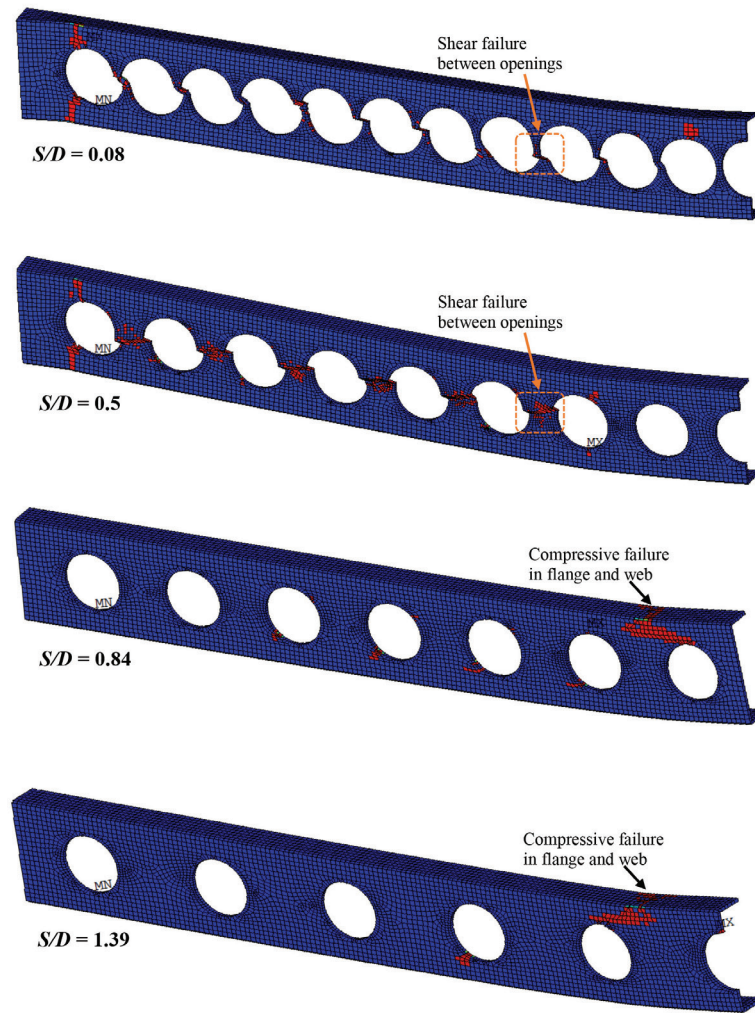
icant reduction in the channel web area. **Figure 12** shows the failure modes of the channel at different values of  $S/D$ . For  $S/D$  less than 0.84, channel failure occurred by shear between the openings. As  $S/D$  was increased beyond 0.84, shear failure was eliminated and compressive crushing of the flange and web governed at a higher load. Based on the anal-



**Figure 10.** Failure in channels with different diameter  $D$  of circular web opening and different composite degrees. Note: Red elements indicate a Hashin parameter of 1.0 (failure).  $d_w$  = unsupported channel depth; MN = minimum stress in contour; MX = maximum stress in contour.



**Figure 11.** Effect of the clear spacing  $S$  of circular web opening of  $0.6d_w$  diameter. Note:  $d_w$  = unsupported channel depth;  $D$  = diameter of circular web opening. 1 mm = 0.0394 in.; 1 kN = 0.225 kip.



**Figure 12.** Failure in channels with different clear spacing  $S$  of circular web opening. Note: Red elements indicate a Hashin parameter of 1.0 (failure).  $D$  = diameter of circular web opening; MN = minimum stress in contour; MX = maximum stress in contour.

ysis, providing circular holes in the web with a maximum diameter of 0.6 times the unsupported channel depth (equal to the insulation thickness) and with a clear spacing not less than 0.84 times the hole diameter is recommended. This will ensure a panel strength equivalent to that of a panel with an unperforated GFRP channel.

### Introducing web openings in the GFRP channel: Shape of the openings

Different geometries of web opening are discussed in this section, namely circular, diamond, hexagonal, and square. For all four geometries, the area of the hole was kept constant and equal to the area of the optimal circular opening established earlier with  $D/d_w$  of 0.6. The number of holes was also kept the same for all shapes. **Figure 13** shows the load-deflection responses for all four panels. The figure shows that the stiffness of the panel was not significantly affected by the opening

shape. The maximum load  $P_{max}$ , however, was greatly affected by the opening shape.

The circular opening provided the highest load, at  $P_{max} = 70.4$  kN (15.8 kip), followed by the diamond shape at  $P_{max} = 59.9$  kN (13.5 kip) (or 85% of the circular hole panel), followed by the hexagonal shape at  $P_{max} = 55.9$  kN (12.6 kip) (or 79% of the circular hole panel), and then by the square shape at  $P_{max} = 54.7$  kN (12.3 kip) (or 77% of the circular hole panel).

**Figure 14** displays the failure modes for channels with the four examined shapes. In the channel with circular openings, failure was by flange and web compressive crushing near the midspan section. For the channels with hexagonal and square openings, similar compressive failures occurred, but the failures were farther away from midspan. For the channel with diamond-shaped openings, failure was by shear between the openings.

## Assessment of degree of composite action

The previous sections assessed the effect of a number of parameters on the strength, stiffness, and failure mode of the concrete sandwich panel. In this section, the effects of selected parameters on the degree of composite action  $k$  are assessed. The degree of composite action was calculated from the following equation using the load method:<sup>5</sup>

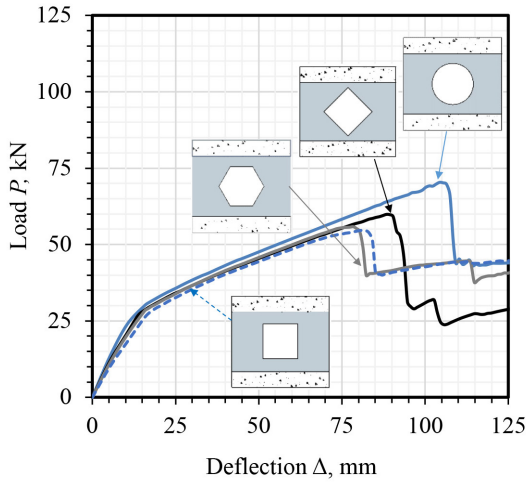
$$k = \frac{P_{max}(\text{partial}) - P_{max}(\text{NC})}{P_{max}(\text{FC}) - P_{max}(\text{NC})} \times 100$$

where

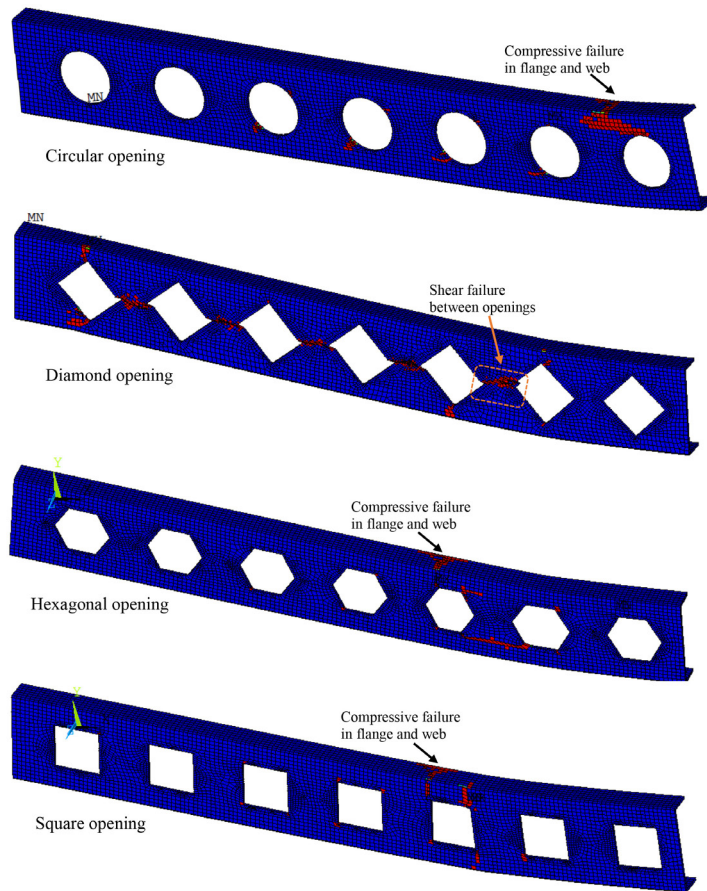
$P_{max}(\text{partial})$  = maximum load from the FEA models for the partially composite panel

$P_{max}(\text{NC})$  = maximum load from the FEA models for the noncomposite case

$P_{max}(\text{FC})$  = maximum load from the FEA models for the fully composite case



**Figure 13.** Plots of load  $P$  compared with deflection  $\Delta$  for different shapes of channel web opening. Note: 1 mm = 0.0394 in.; 1 kN = 0.225 kip.



**Figure 14.** Failure in channels with different shapes of web opening. Note: Red elements indicate a Hashin parameter of 1.0 (failure). MN = minimum stress in contour; MX = maximum stress in contour.

Figure 15 shows the variation of  $k$  when two parameters are varied: the unsupported channel depth-to-thickness ratio  $d_w/t_w$  varying from 10 to 100 and the diameter of web opening-to-unsupported channel depth ratio  $D/d_w$  varying from 0 to 1. For  $d_w/t_w$ ,  $k$  increased from 34% to 99% when  $d_w/t_w$  increased from 10 to 30. The degree of composite action decreased to  $k = 26\%$  when  $d_w/t_w$  increased from 30 to 50 and then increased to an average  $k$  of 80% for  $d_w/t_w$  greater than 50. This inconsistent variation in  $k$  is likely due to the transition of the channel failure mode from material rupture to stability failure, which occurs at different values of  $d_w/t_w$  for the fully composite, partially composite, and noncomposite panels (Fig. 3). Even the stability failure was also somewhat inconsistent, occurring at local regions in some cases or spread through the entire channel in other cases (Fig. 5). The bottom graph in Fig. 16 shows that  $k$  seems to vary by a small amount, from  $k$  equals 45% to  $k$  equals 61%, as  $D/d_w$  increases from 0 to 0.6 and then decreases slightly at higher values of  $D/d_w$ . This variation is because the critical value of

$D/d_w$  is different for the partially composite and noncomposite cases (Fig. 9).

## Conclusion

This study presents comprehensive FEA models developed to study the structural behavior of concrete sandwich panels with connectors made of a commercially available C-shaped GFRP channel section. The models included various features, such as concrete nonlinear response in compression, tension stiffening, cracking and crushing failures, Hashin failure criteria of the GFRP channel, interfacial modeling of different parts in contact, geometric nonlinearity, and stability failure of the channel. The models were validated using the experimental results reported in the companion paper, and very good agreements were observed. A comprehensive parametric study was carried out to examine the effects of several key parameters. Based on the results obtained, the following conclusions are drawn:

- For a given unsupported channel depth  $d_w$  (equal to the insulation thickness), reducing the web thickness of the channel section  $t_w$  reduced flexural strength and stiffness of the panel. Increasing  $d_w/t_w$  from 10 to 50 resulted in a sharp reduction in strength of 82% for the partially composite panel. The rate of reduction decreased thereafter as the increase of  $d_w/t_w$  from 50 to 100 resulted in a 9% strength reduction. The failure mode changed from material to stability failure of the channel section at  $d_w/t_w$  of 30.
- Increasing the flange thickness  $t_f$  of the GFRP channel relative to  $t_w$  resulted in an increase in flexural strength and stiffness of the partially composite panel. Increasing  $t_f/t_w$  from 1 to 2 increased the strength by 25%.
- Introducing holes in the web of the GFRP channel to reduce thermal bridging can be achieved without compromising the structural capacity of the panel. Circular, square, hexagonal, and diamond-shaped cuts of equal area were compared. The optimal cut shape that gave the highest flexural strength of the panel was the circular shape.
- Both the diameter  $D$  and clear spacing  $S$  of the circular holes in the GFRP channel web were varied independently. The optimal values of  $D/d_w$  and  $S/D$  for the partially composite panels that provide similar strength to that of the panels with an unperforated channel were 0.6 and 0.83, respectively. Smaller values of  $S/D$  resulted in premature shear failure between the holes at a reduced strength.
- Increasing concrete compressive strength  $f'_c$  from 20 to 60 MPa (2.9 to 8.7 ksi) does not affect the behavior of a partially composite panel. For a fully composite panel, however, increasing  $f'_c$  led to an increase in the postyielding stiffness and maximum load  $P_{max}$ , which increased by 30% when  $f'_c$  increased from 20 MPa to 60 MPa.

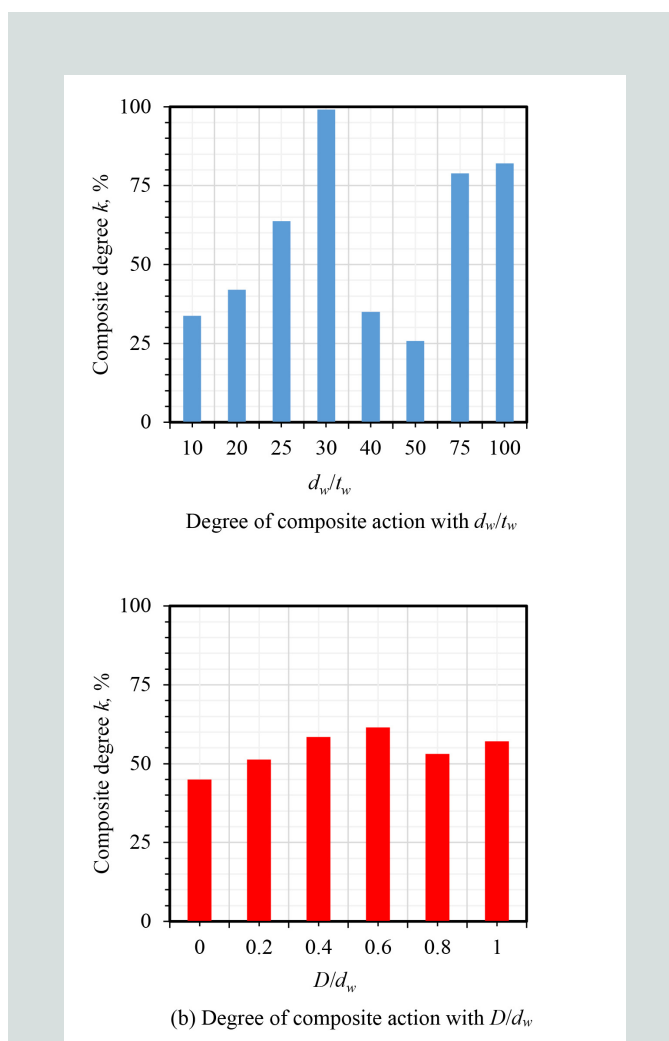


Figure 15. Variation of the degree of composite action  $k$  with  $d_w/t_w$  and  $D/d_w$  ratios. Note:  $D$  = diameter of circular web opening;  $d_w$  = unsupported channel depth;  $t_w$  = channel web thickness.



- Doubling the wythe steel reinforcement ratio  $\rho_s$  from 1% to 2% resulted in a 13% increase in the flexural strength of the partially composite panel, whereas increasing the concrete compressive strength from 20 to 60 MPa (2.9 to 8.7 ksi) had an insignificant effect on flexural strength.

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- $E_2$  = elastic modulus in matrix direction
- $E_c$  = concrete elastic modulus
- $E_f$  = elastic modulus of the GFRP channel
- $E_s$  = elastic modulus of steel
- $f_c$  = compressive stress at any strain
- $f'_c$  = concrete compressive strength
- $f_t$  = maximum concrete tensile stress
- $f_y$  = yield stress of steel reinforcement
- $G_{12}$  = shear modulus
- $k$  = degree of composite action
- MN = minimum stress in contour
- MX = maximum stress in contour
- $N$  = normal contact pressure
- $P$  = load
- $P_{max}$  = maximum load
- $P_{max}(FC)$  = maximum load from the FEA models for the fully composite case
- $P_{max}(NC)$  = maximum load from the FEA models for the noncomposite case
- $P_{max}(\text{partial})$  = maximum load from the FEA models for the partially composite panel
- $S$  = clear spacing between the circular openings in the channel
- $S^L$  = in-plane shear strength
- $t_f$  = channel flange thickness
- $t_w$  = channel web thickness
- $U_x$  = displacement in the x direction
- $U_y$  = displacement in the y direction
- $X^C$  = compressive strength in fiber direction
- $X^T$  = tensile strength in fiber direction
- $Y^C$  = compressive strength in matrix direction

## Notation

$COHE$  = interface cohesion when the contact pressure is equal to 0

$d_w$  = unsupported channel depth

$D$  = diameter of the circular opening in the channel

$E_1$  = elastic modulus in fiber direction

$Y^T$	= tensile strength in matrix direction
$Z$	= slope of the linear descending portion of the stress–strain curve for concrete in compression
$\Delta$	= midspan deflection
$\varepsilon$	= strain
$\varepsilon_0$	= concrete compressive strain at $f'_c$
$\varepsilon_{50u}$	= concrete compressive strain at $f_c$ equal to $0.5f'_c$
$\varepsilon_c$	= concrete strain
$\varepsilon_t$	= strain at the maximum concrete tensile stress
$\varepsilon_u$	= ultimate concrete compressive strain
$\varepsilon_{uf}$	= ultimate strain in the GFRP channel
$\varepsilon_y$	= yield strain for the steel reinforcement
$\theta_y$	= rotation in the y direction
$\theta_z$	= rotation in the z direction
$\mu$	= coefficient of friction
$\nu$	= Poisson's ratio
$\nu_{12}$	= major Poisson's ratio
$\rho_s$	= steel reinforcement ratio
$\sigma$	= stress
$\sigma_c$	= concrete compressive stress
$\sigma_{ij}$	= acting normal stress
$\sigma_t$	= concrete tensile stress
$\sigma_{uf}$	= ultimate stress of GFRP channel
$\sigma_y$	= yield stress of steel reinforcement
$\tau$	= interface shear stress
$\tau_{ij}$	= acting shear stress

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## Abstract

The effectiveness of glass-fiber-reinforced polymer (GFRP) pultruded channel sections as shear connectors in precast concrete sandwich walls has been demonstrated experimentally in the companion paper, “A New Studed Precast Concrete Sandwich Wall with Embedded Glass-Fiber-Reinforced Polymer Channel Sections: Part 1, Experimental Study.” In this paper, three-dimensional nonlinear finite element analysis models of the previously tested panels are developed, verified, and used in a comprehensive parametric study. The models consider accurate constitutive laws for all materials, interfacial relations for different parts in contact, and different failure modes, including material and stability failure of GFRP channels.

The parametric study showed that increasing the ratio of the unsupported channel depth  $d_w$  to GFRP channel web thickness  $t_w$  led to a decrease in flexural strength and a shift in failure mode from material to stability failure of the GFRP connector, which occurs at  $d_w/t_w$  of 30 in the partially composite panel. When the channel flange thickness and the wythe steel reinforcement ratio were independently doubled, flexural strength increased by 25% and 13%, respectively. Concrete compressive strength had an insignificant effect on partially composite panel strength. To increase thermal efficiency without reducing structural effectiveness, the use of circular perforations in the GFRP channel web was explored. It was found that openings with a diameter  $D$  up to  $0.6d_w$  and a clear spacing  $S$  not less than  $0.84D$  can be effectively introduced without reducing the structural strength of the panel. Circular openings were shown to be more effective than diamond-shaped, hexagonal, or square openings.

## Keywords

Composite action, finite element, GFRP, glass-fiber-reinforced polymer, sandwich panel, shear connector, stud, thermal efficiency.

## Review policy

This paper was reviewed in accordance with the Precast/Prestressed Concrete Institute’s peer-review process.

## Reader comments

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